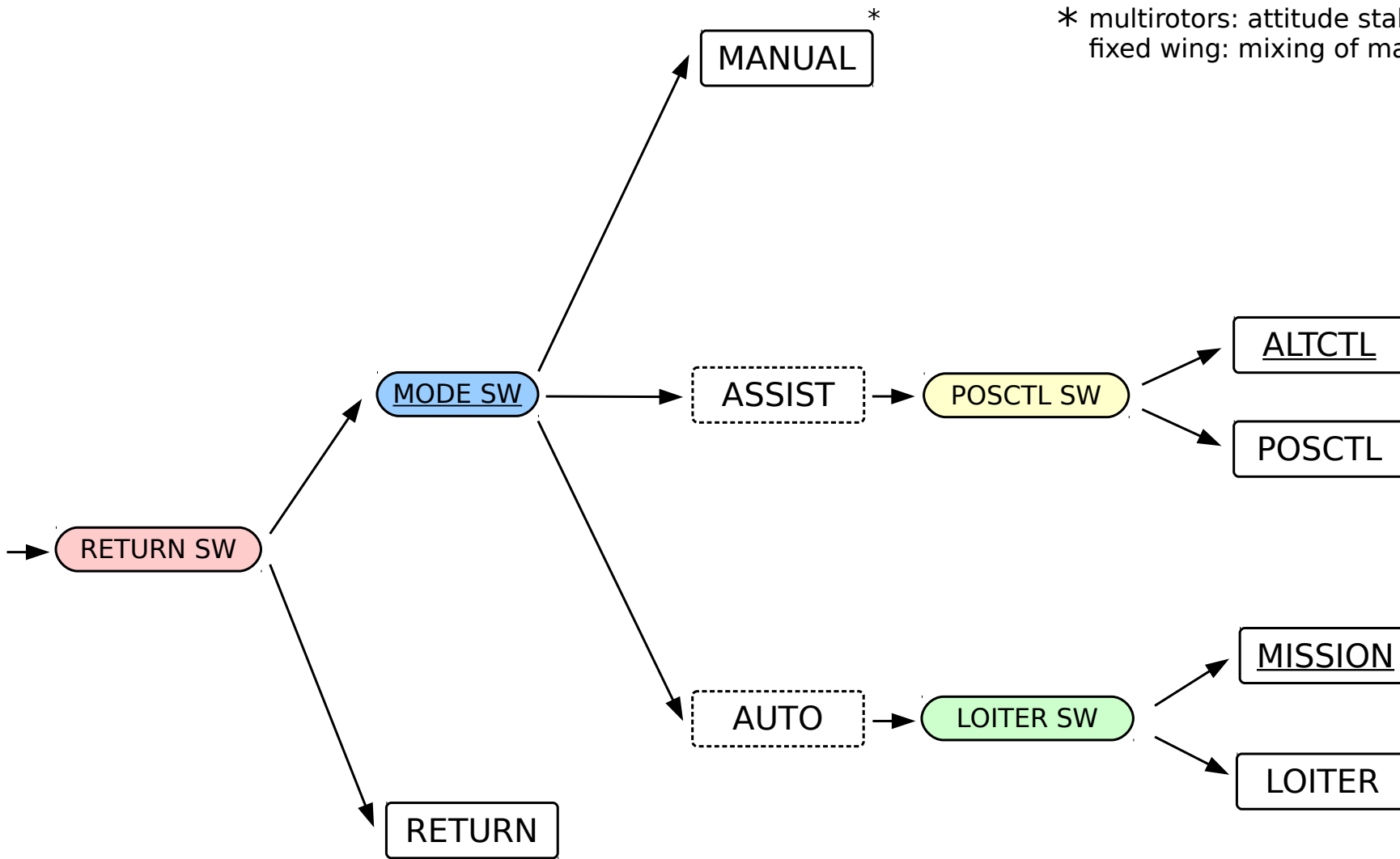


\* multirotors: attitude stabilized,  
fixed wing: mixing of manual inputs



MODE SW

Main mode switch (mandatory, 3 position)

POSCTL SW

Position control switch (optional, 2 position, default value if not present)

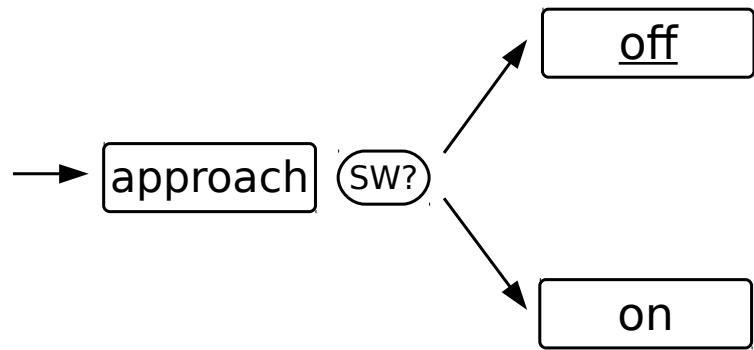
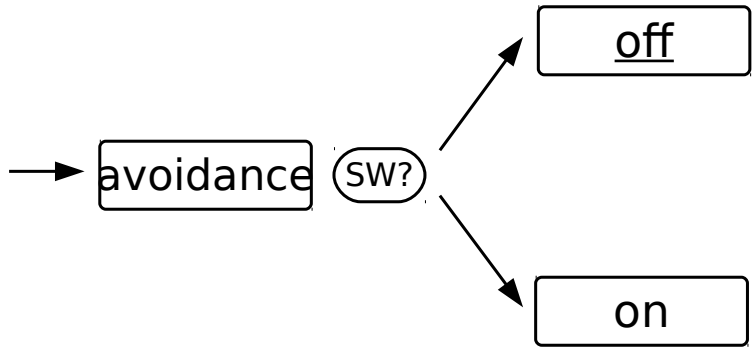
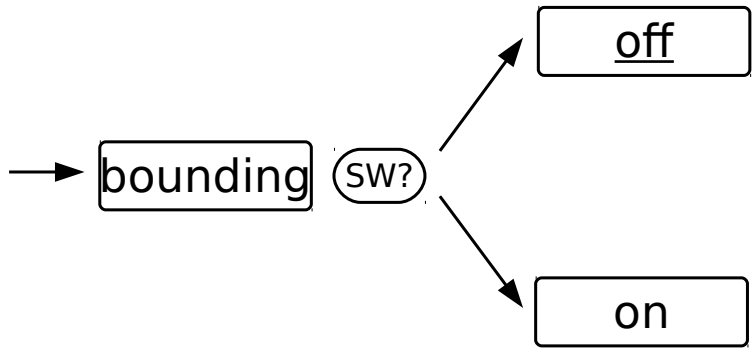
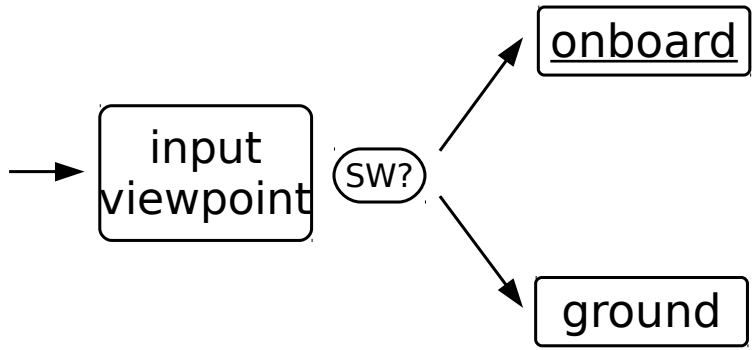
RETURN SW

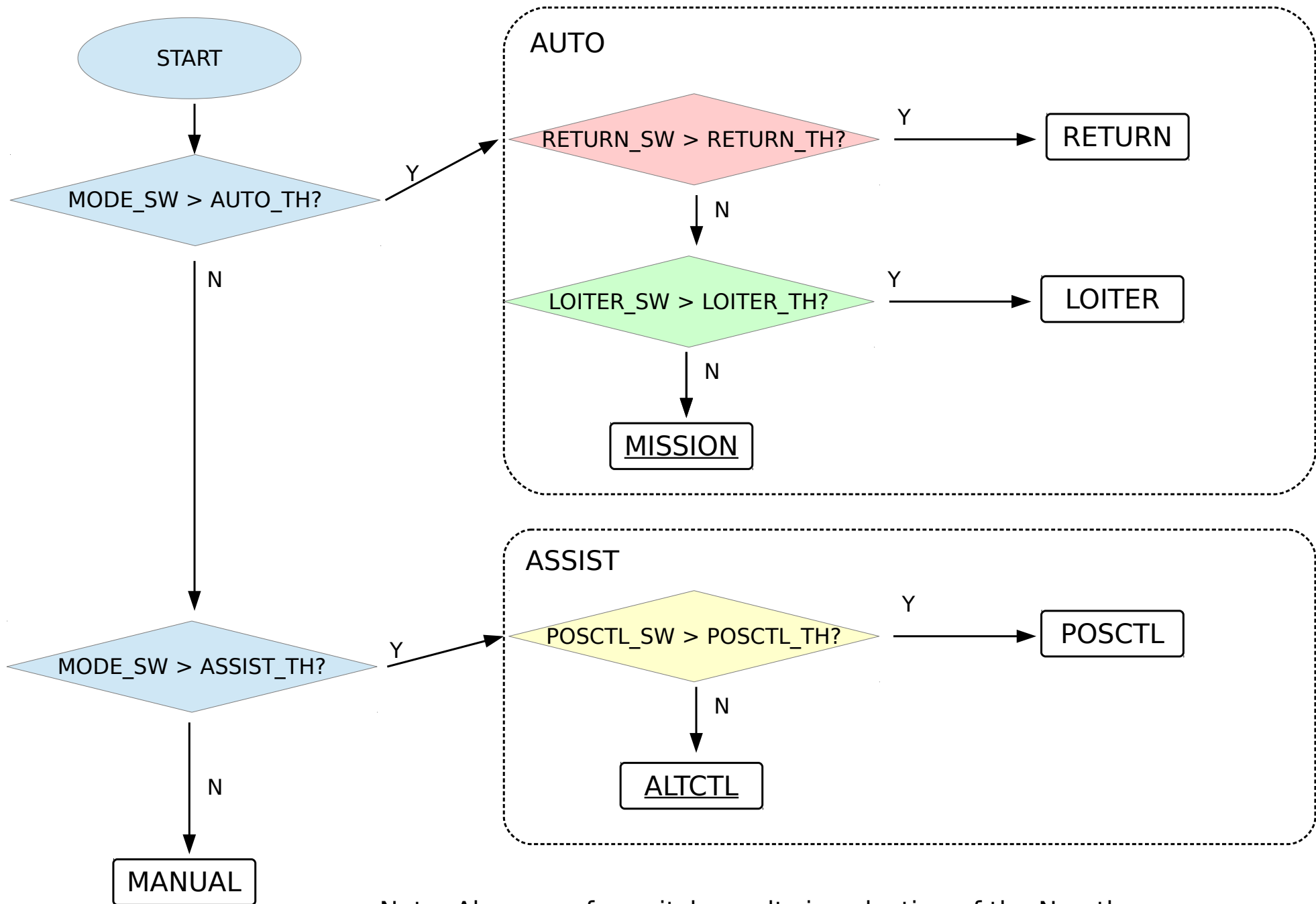
Return switch (optional, 2 position, default value if not present)

LOITER SW

Loiter (pause mission) switch (optional, 2 position, default value if not present)

increasing autonomy





Note: Absence of a switch results in selection of the N path.